

Turing machines

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Introduction

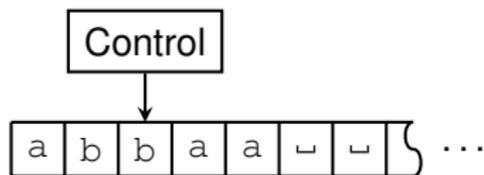
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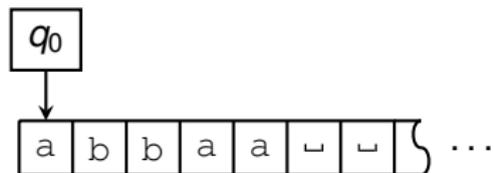
A Turing machine is like a finite automaton, with three major differences:

- ▶ It can **write** to its tape;
- ▶ It can move both left and right;
- ▶ The tape is **infinite** in one direction.

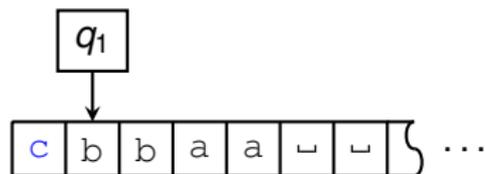


Initially, the input is provided on the left-hand end of the tape, and followed by an infinite sequence of blank spaces ("␣").

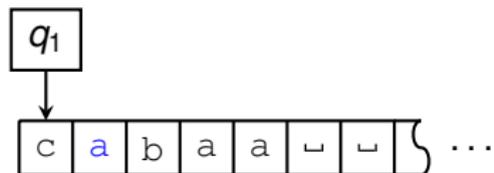
Example



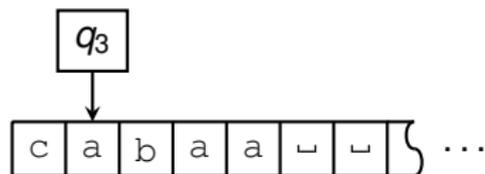
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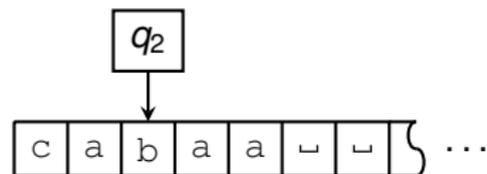
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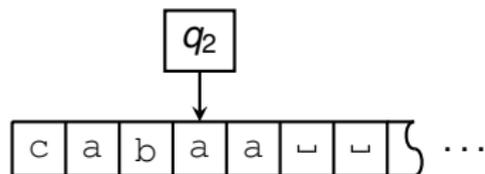
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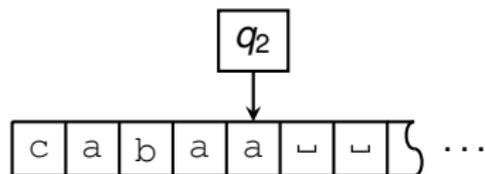
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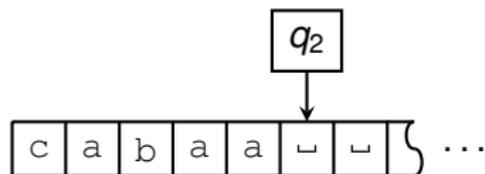
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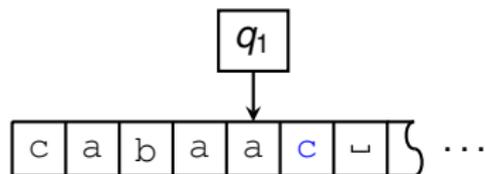
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Alan Turing (1912-1954)

- ▶ **1936:** Invented the Turing machine and the concept of computability.
- ▶ **1939-1945:** Worked at Bletchley Park on cracking the Enigma cryptosystem and others.
- ▶ **1946-1954:** Work on practical computers, AI, mathematical biology, ...
- ▶ **1952:** Convicted of indecency. Died of cyanide poisoning in 1954.
- ▶ **2014:** Received a royal pardon.



Pic: Wikipedia/Bletchley Park

Turing machines

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- ▶ The language $L(M)$ recognised by a Turing machine M is the set

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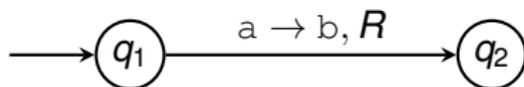
$$\{x \mid M \text{ halts in the accept state on input } x\}$$

- ▶ For some language \mathcal{L} , if there exists a Turing machine M such that $\mathcal{L} = L(M)$, we say that \mathcal{L} is **Turing-recognisable**. (These languages are also sometimes called **recursively enumerable**.)

Describing Turing machines

We can describe a Turing machine by its **state diagram**.

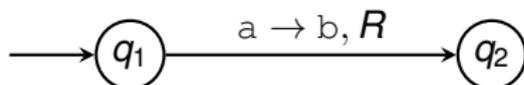
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- ▶ A label of the form

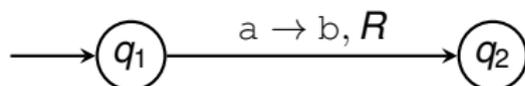
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means that on reading tape symbol a , the machine writes b to the tape and then moves right.

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- ▶ A label of the form

$$a \rightarrow b, R$$

means that on reading tape symbol a , the machine writes b to the tape and then moves right.

- ▶ Another example: a label

$$a, b \rightarrow L$$

means that on reading either tape symbol a or b , the machine doesn't write anything to the tape and then moves left.

Turing machines

Imagine we want to test membership in the language

$$\mathcal{L}_{EQ} = \{w\#w \mid w \in \{0,1\}^*\}.$$

$x \in \mathcal{L}_{EQ}$ if it is made up of two equal bit-strings, separated by a # symbol.

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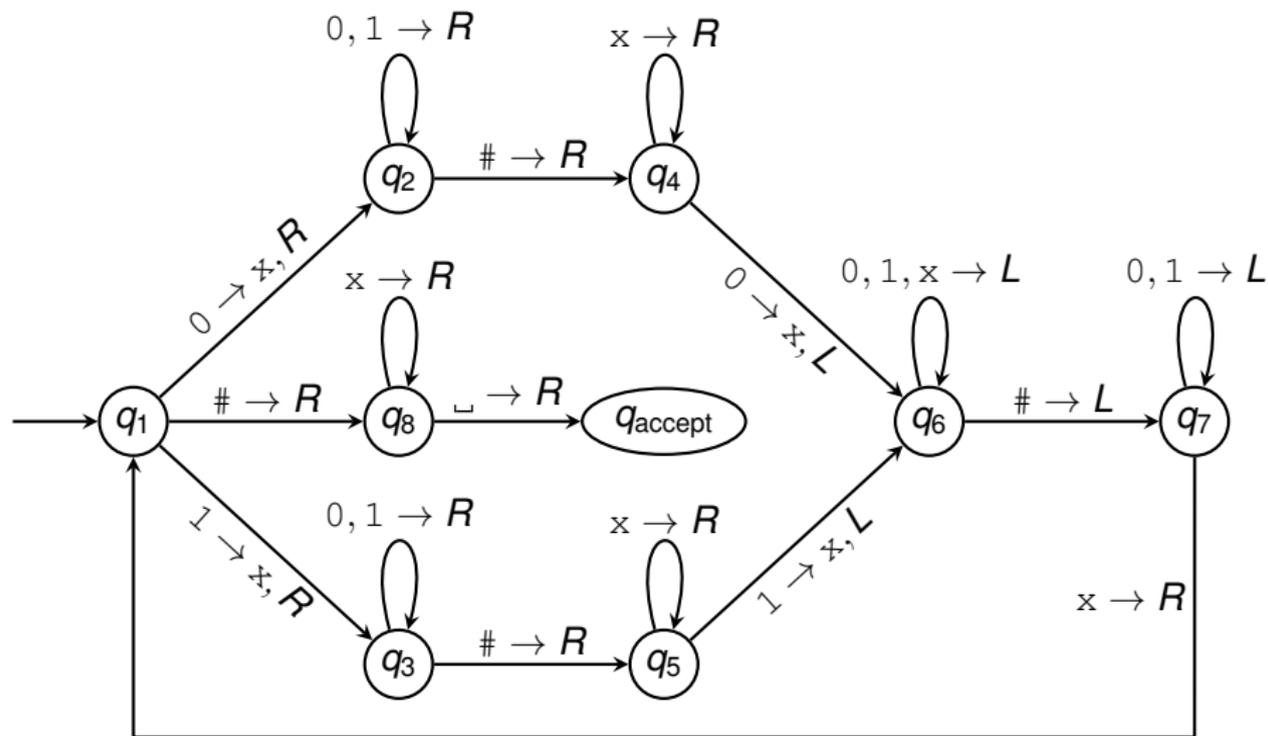
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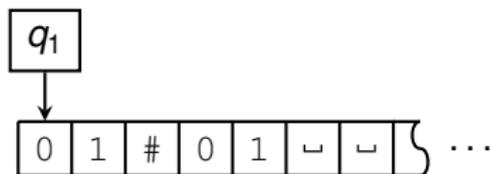
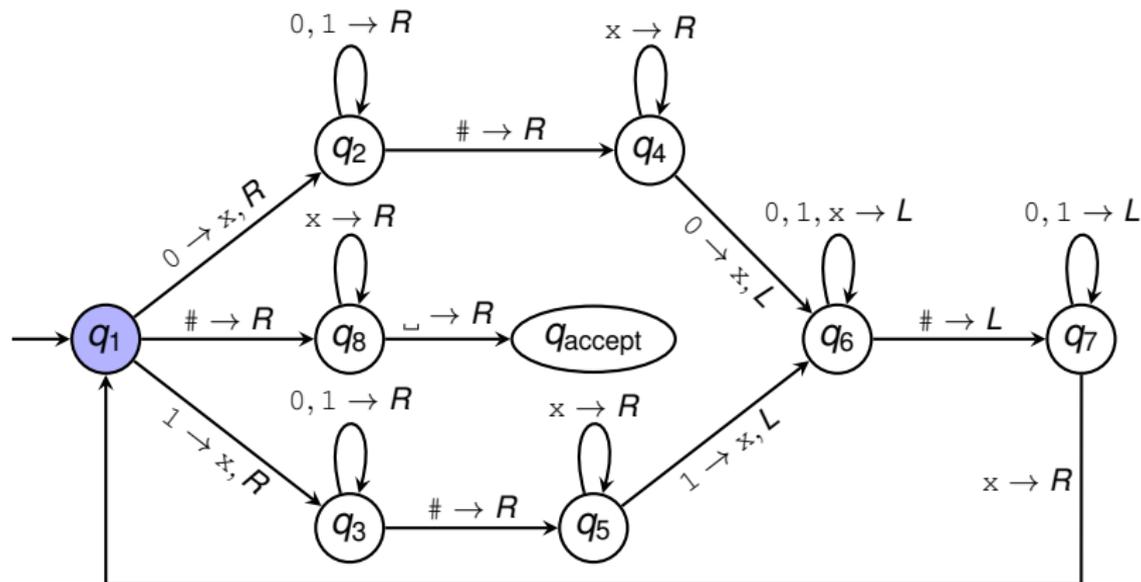
Idea for recognising this language

1. Our algorithm will scan forwards and backwards, testing each corresponding pair of bits either side of the # for equality in turn.
2. We can overwrite each bit with an \times symbol after checking it so we don't check the same bits twice.

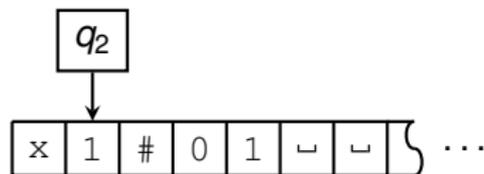
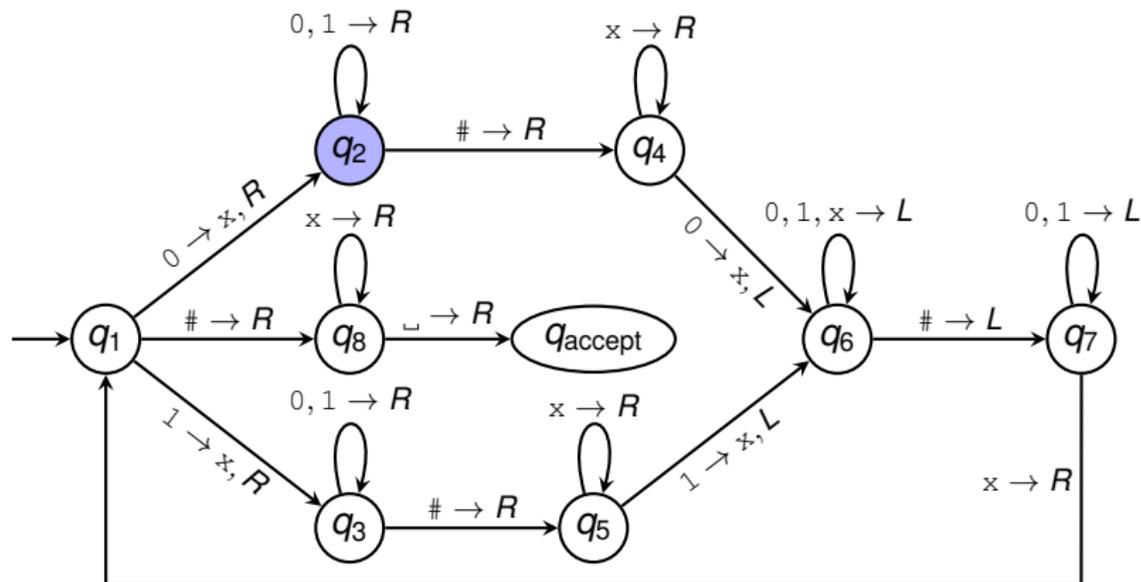
State diagram (Sipser, Figure 3.10)



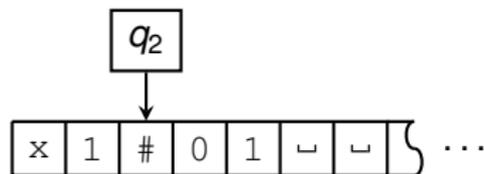
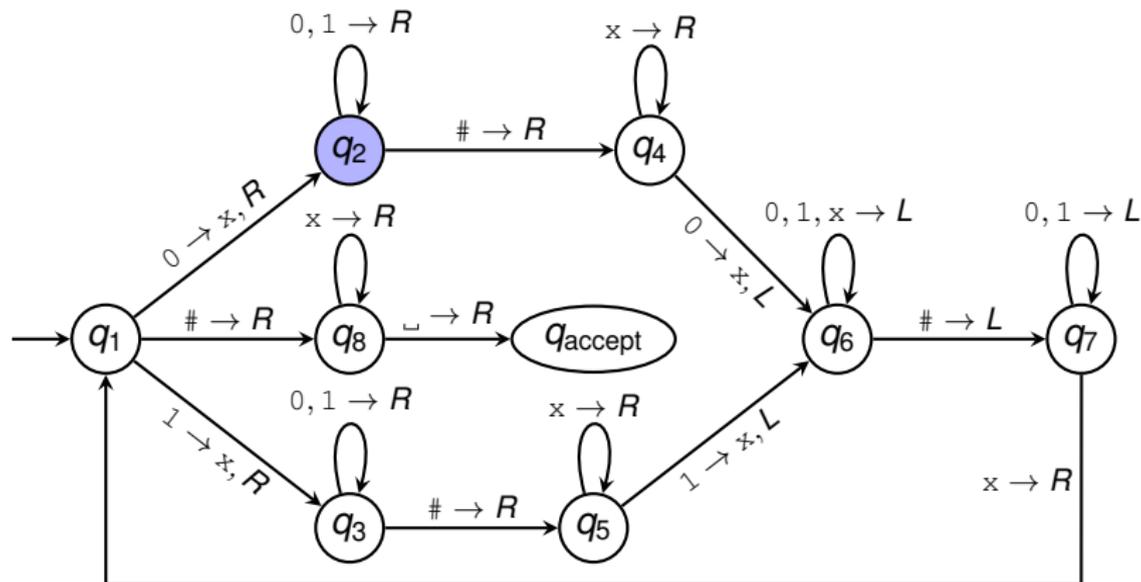
Example: testing whether $01\#01 \in \mathcal{L}_{EQ}$



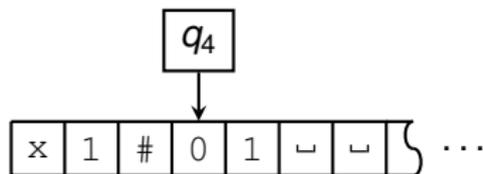
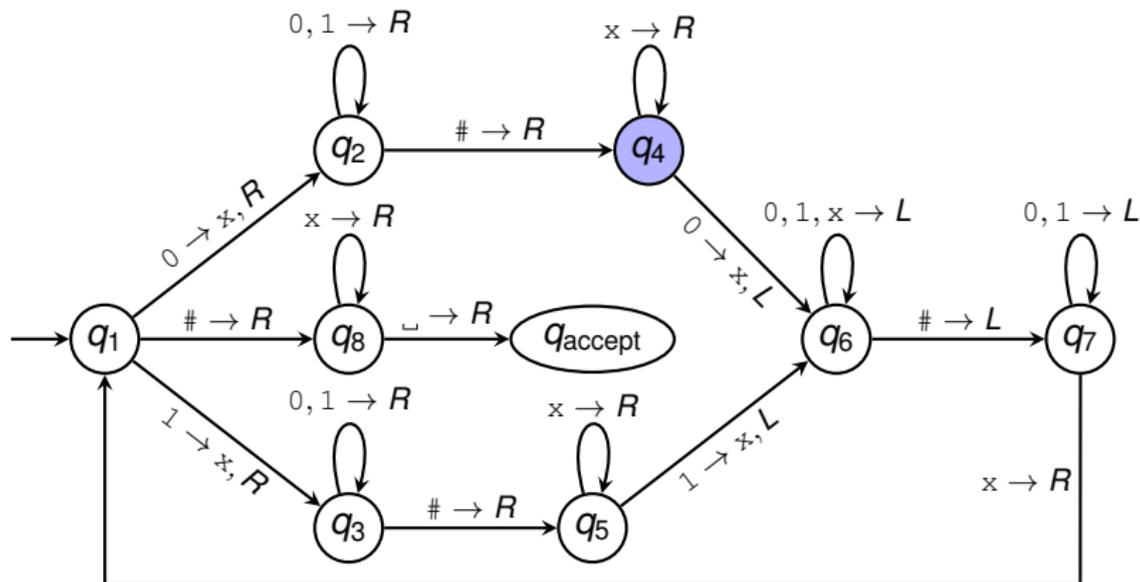
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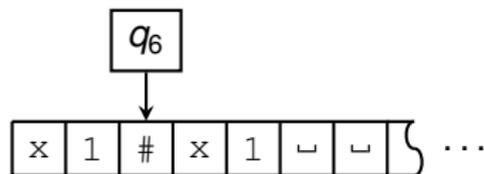
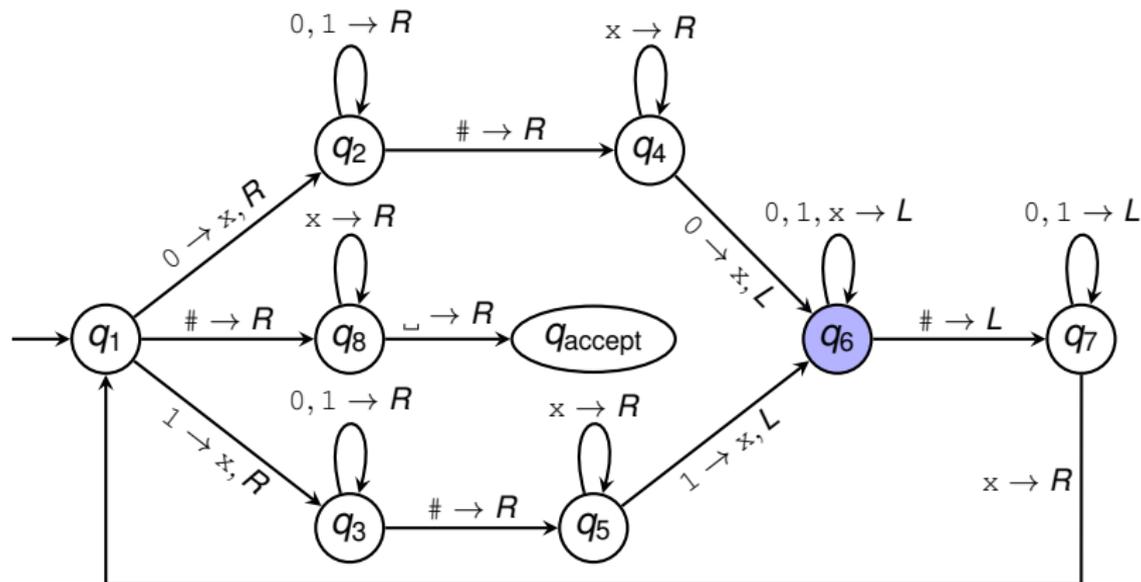
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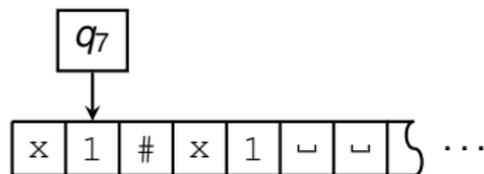
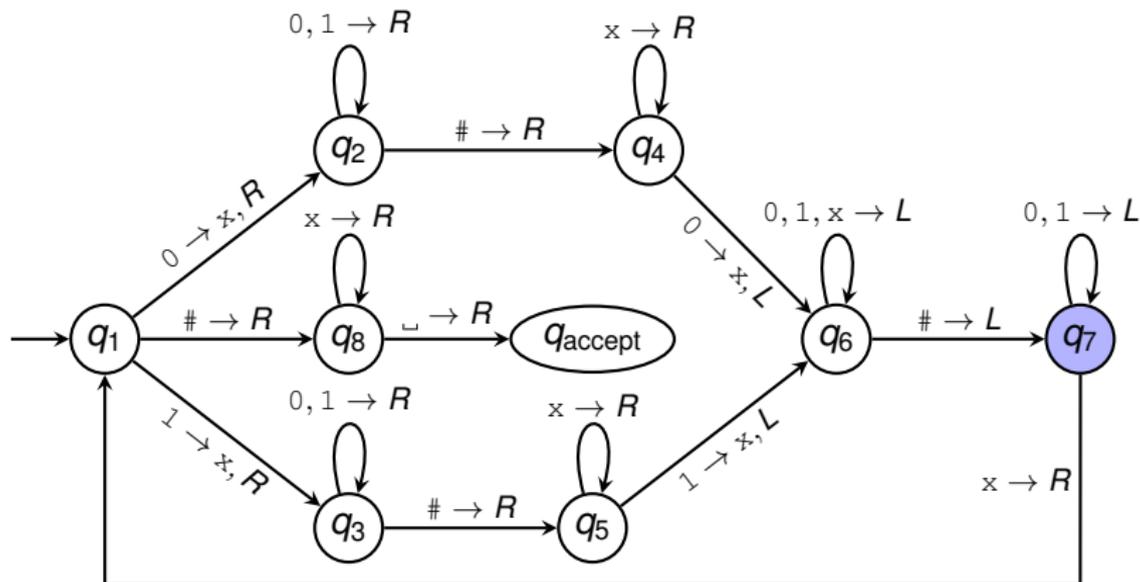
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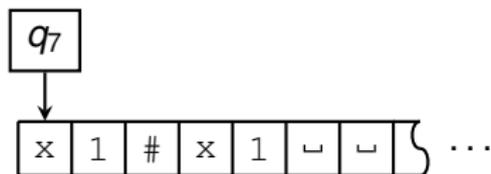
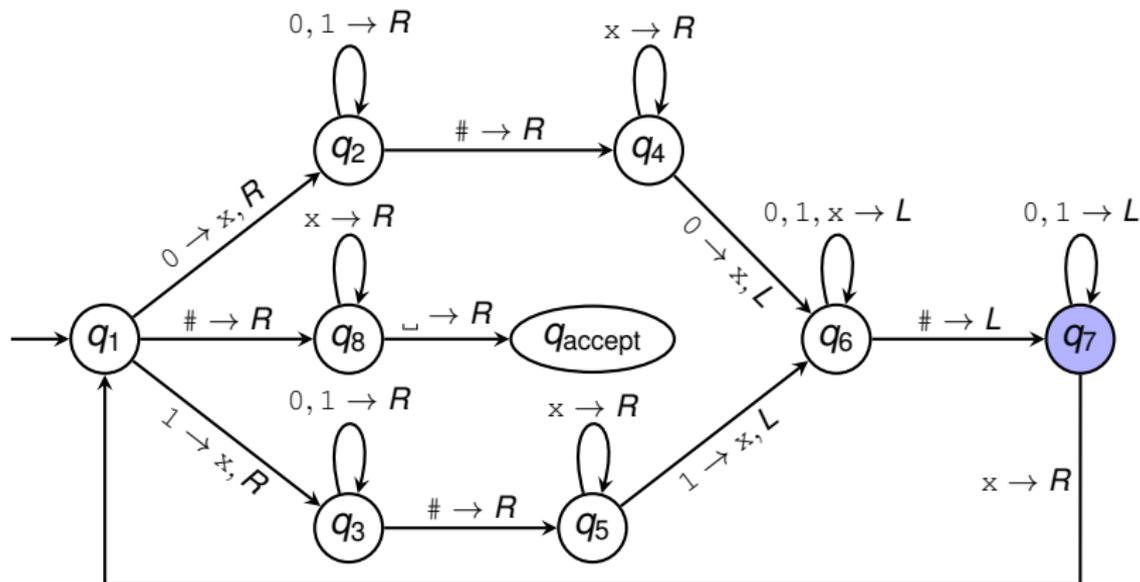
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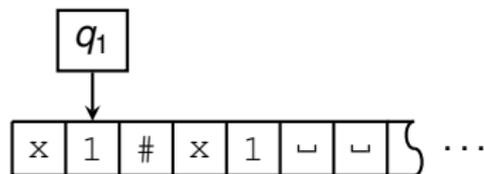
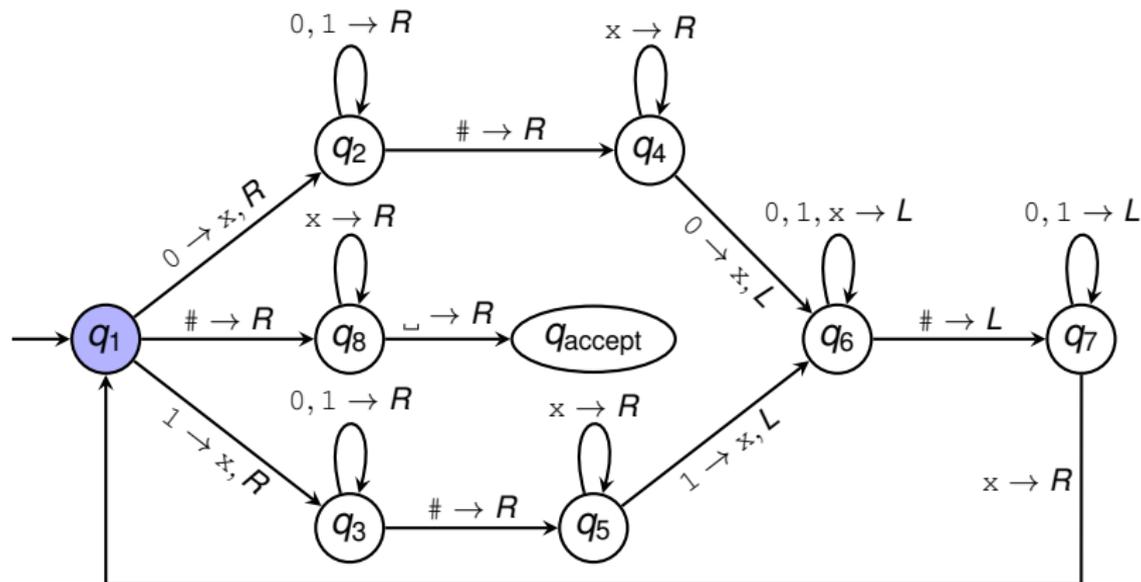
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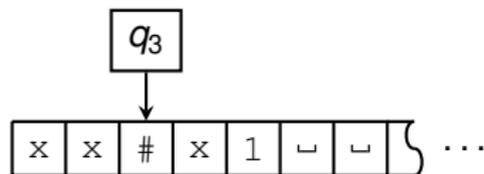
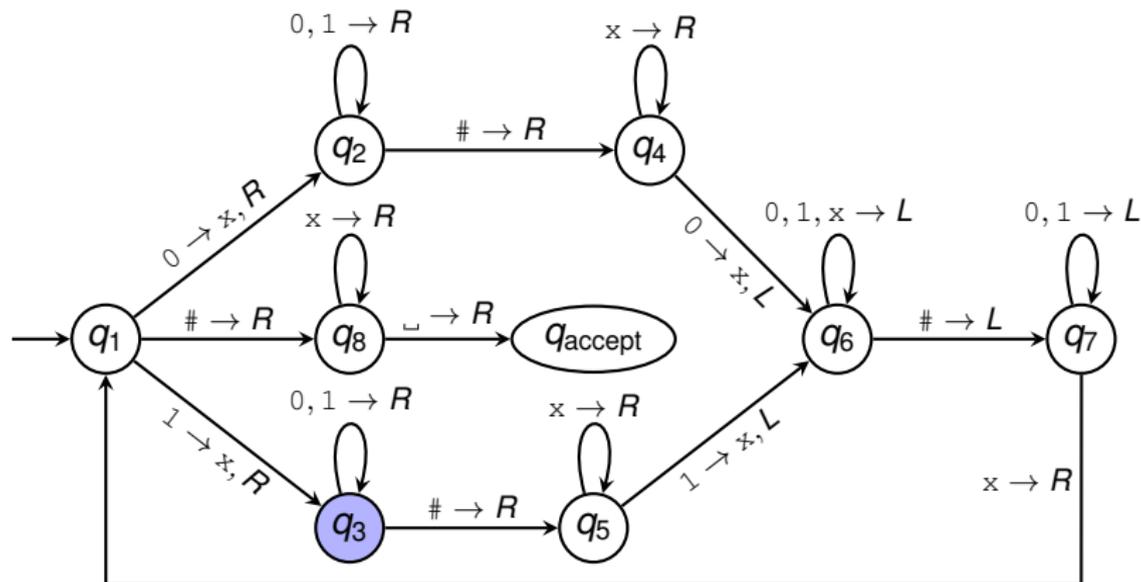
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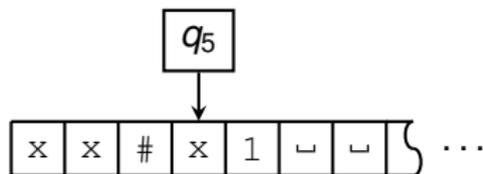
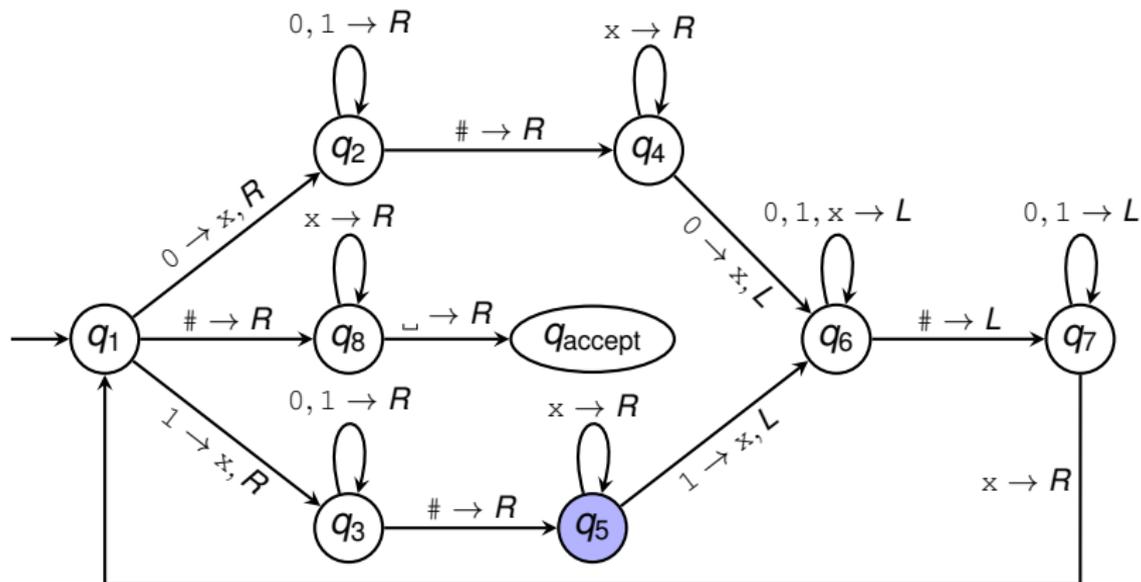
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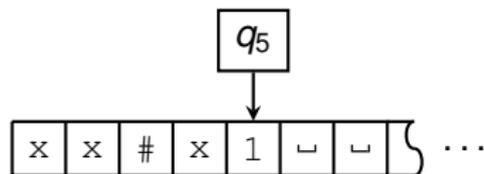
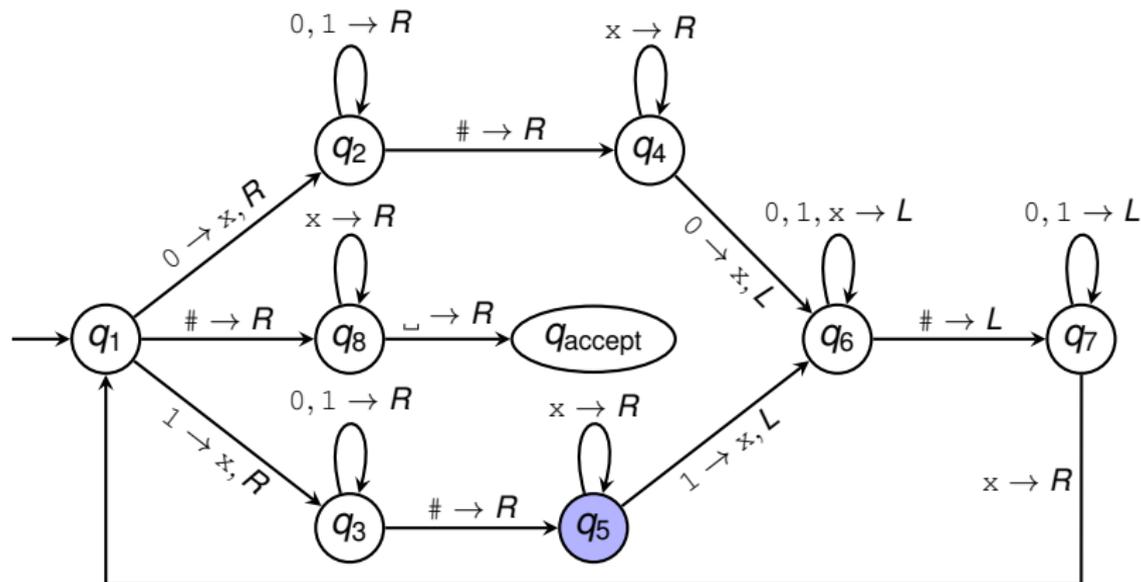
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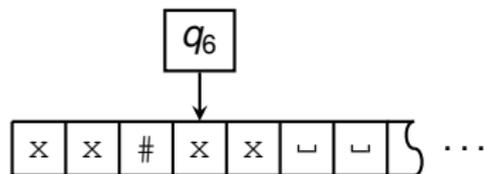
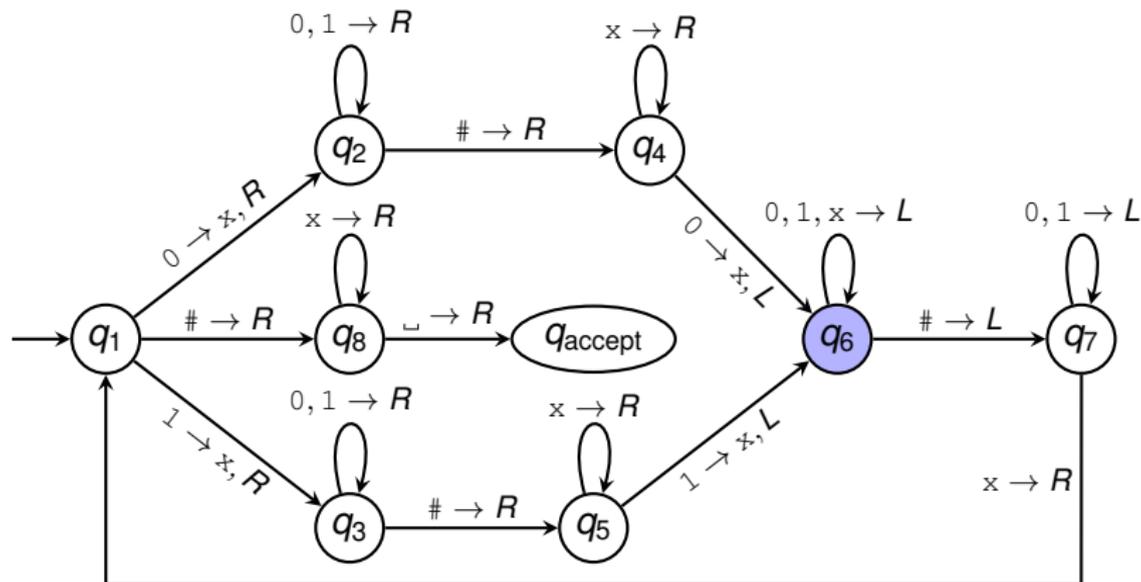
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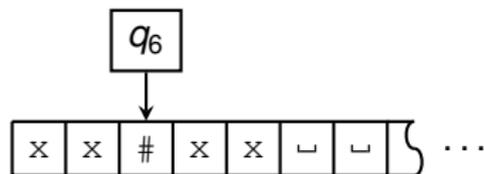
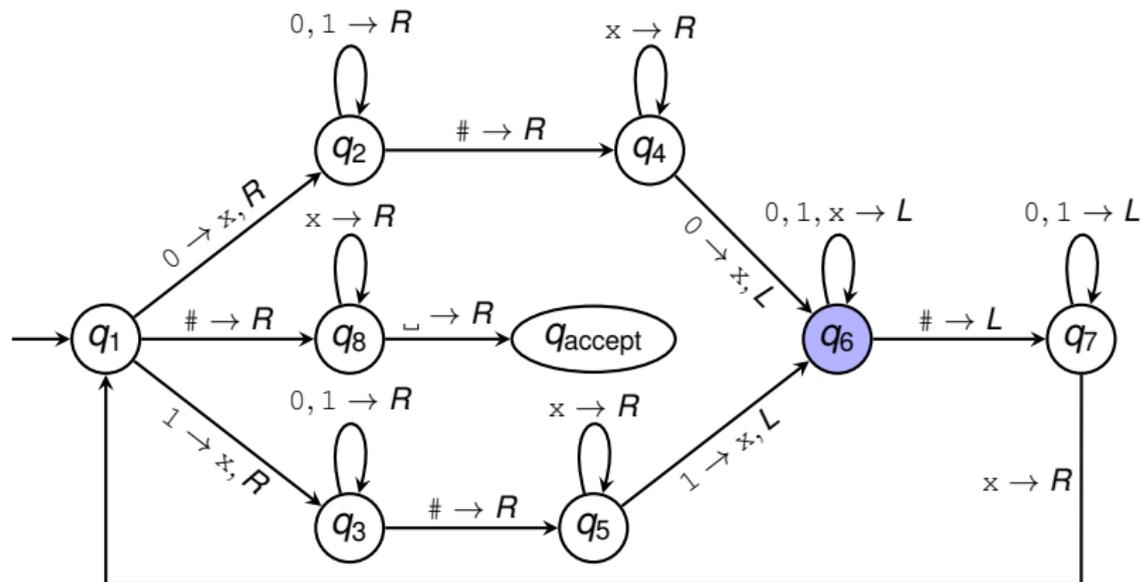
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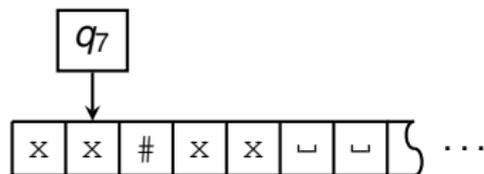
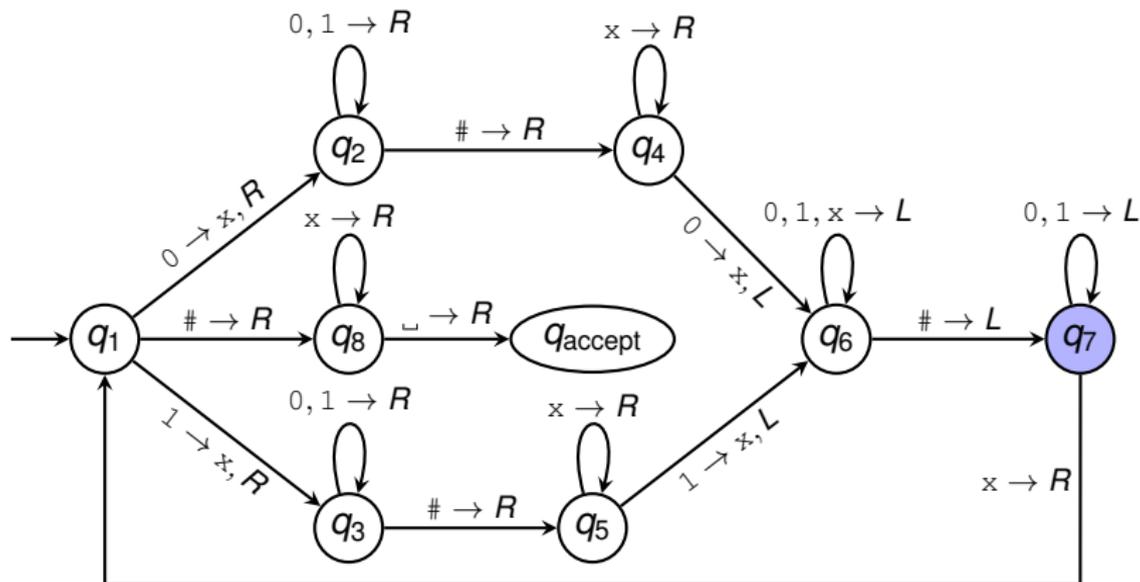
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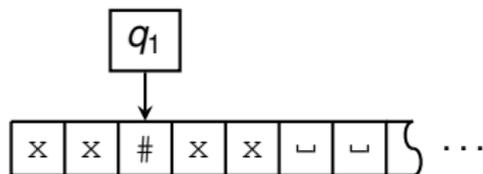
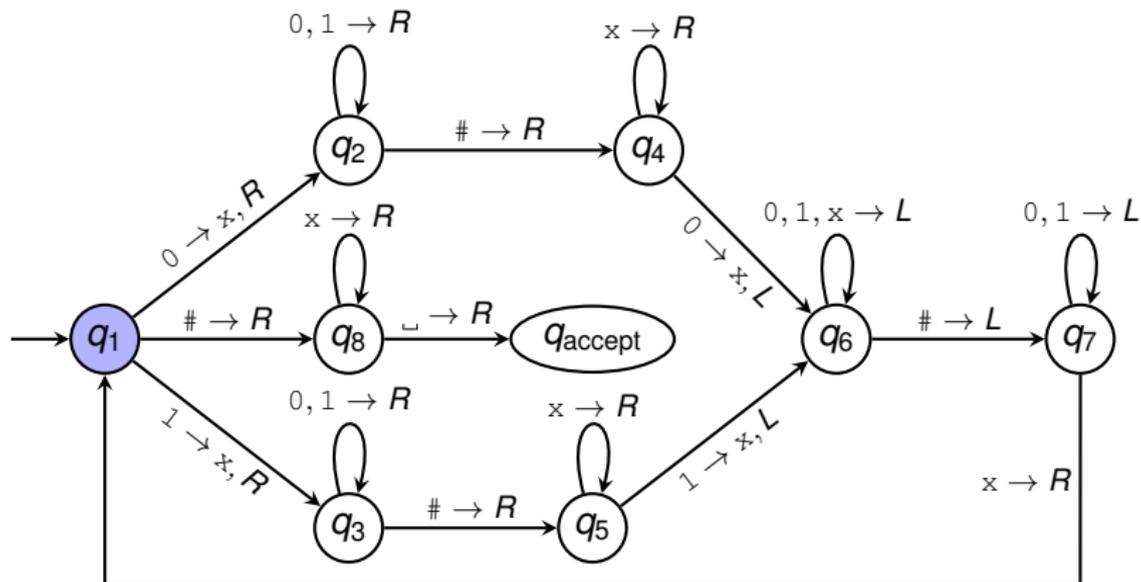
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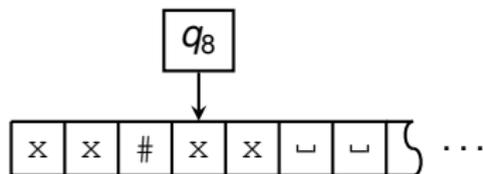
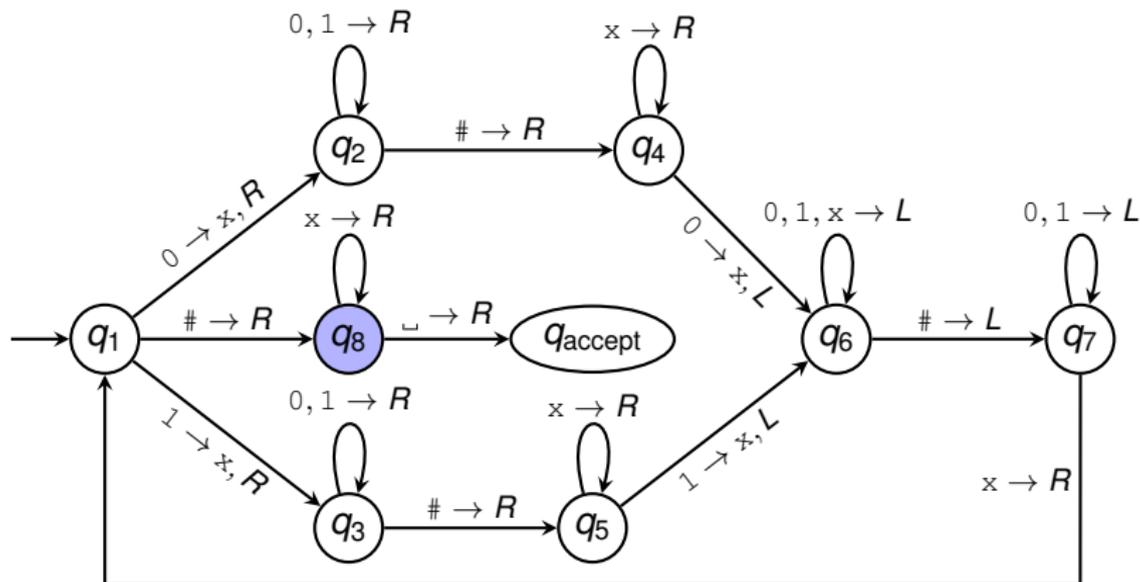
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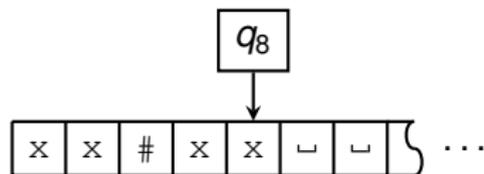
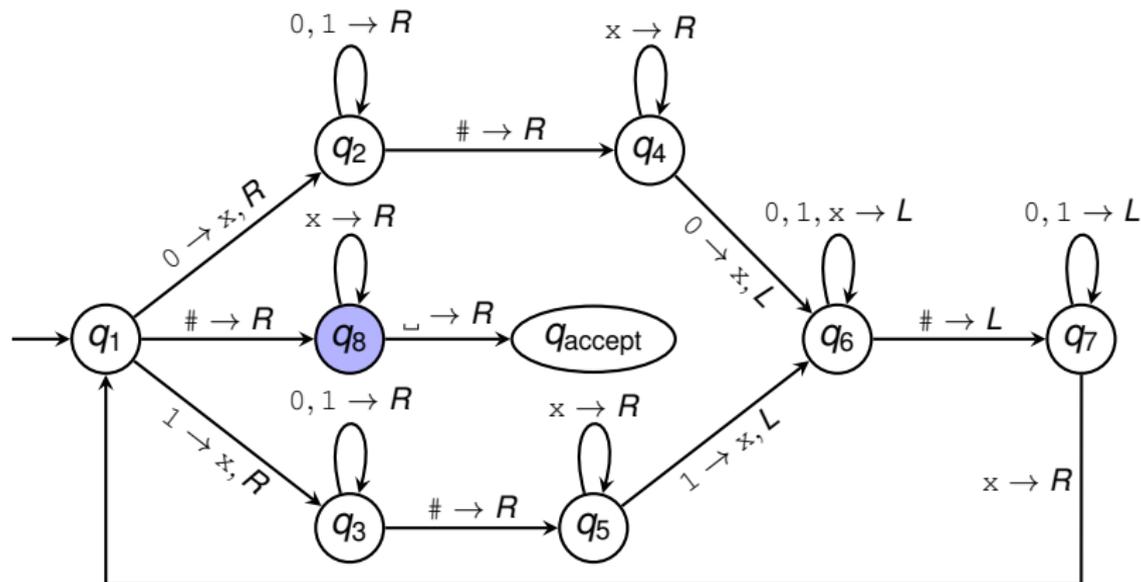
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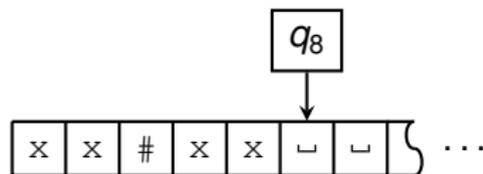
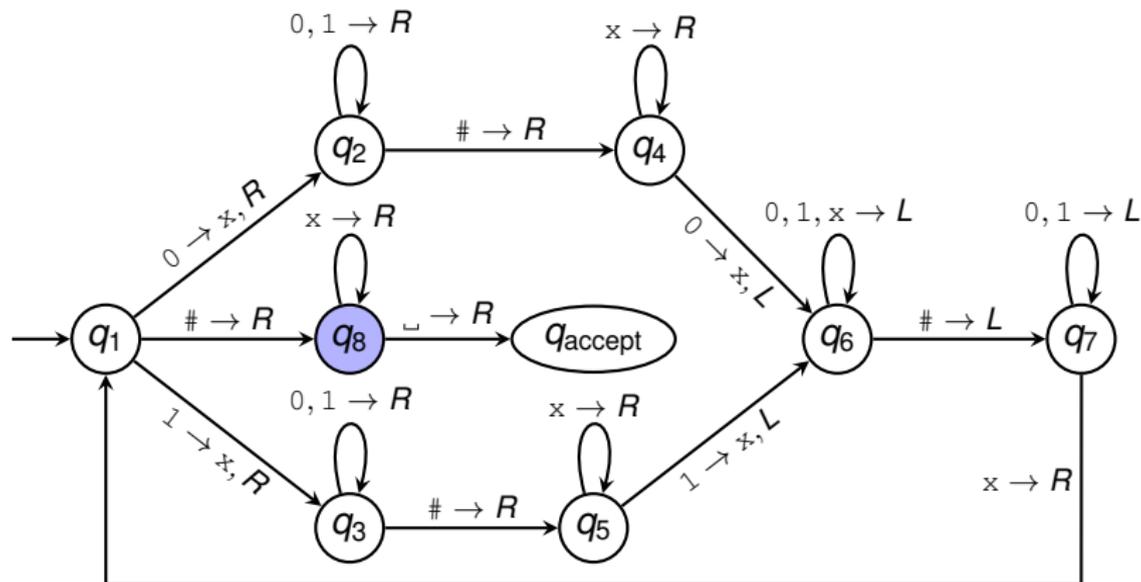
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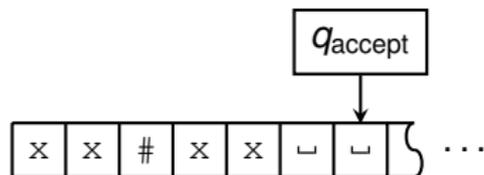
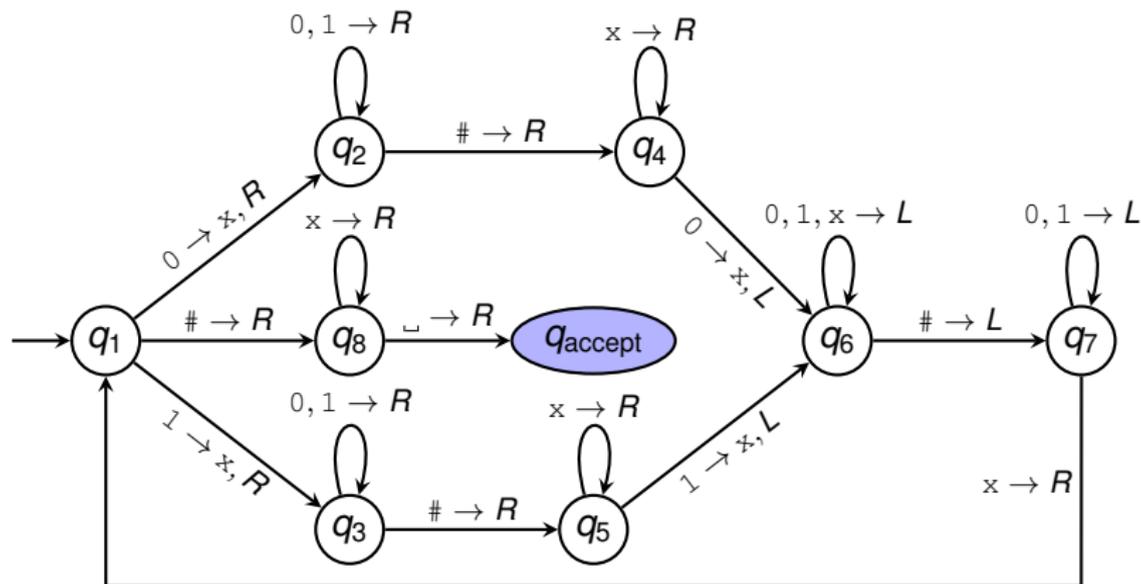
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Turing machines: formal definition

Definition

A **Turing machine** is described by a 7-tuple $(Q, \Sigma, \Gamma, \delta, q_0, q_{\text{accept}}, q_{\text{reject}})$, where:

1. Q is the set of states,
2. Σ is the input alphabet (which must not contain \sqcup),
3. Γ is the tape alphabet, where $\sqcup \in \Gamma$ and $\Sigma \subseteq \Gamma$,
4. $\delta : Q \times \Gamma \rightarrow Q \times \Gamma \times \{L, R\}$ is the transition function,
5. $q_0 \in Q$ is the start state,
6. q_{accept} is the accept state,
7. q_{reject} is the reject state, where $q_{\text{reject}} \neq q_{\text{accept}}$.

Example

The Turing machine we just saw is described by

$(\{q_1, \dots, q_8, q_{\text{accept}}, q_{\text{reject}}\}, \{0, 1, \#\}, \{0, 1, \#, x, \sqcup\}, \delta, q_1, q_{\text{accept}}, q_{\text{reject}})$

where the transition function δ is defined by the table

	0	1	#	x	\sqcup
q_1	q_2, x, R	q_3, x, R	q_8, R		
q_2	q_2, R	q_2, R	q_4, R		
q_3	q_3, R	q_3, R	q_5, R		
q_4	q_6, x, L			q_4, R	
q_5		q_6, x, L		q_5, R	
q_6	q_6, L	q_6, L	q_7, L	q_6, L	
q_7	q_7, L	q_7, L		q_1, R	
q_8				q_8, R	q_{accept}, R

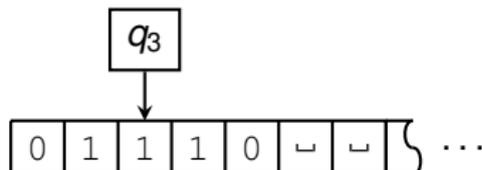
Blank entries in the table correspond to transitions where the machine **rejects**.

Turing machines: formal definition (2)

- ▶ The full description of what a Turing machine M is doing at any point in time is called its **configuration**.
- ▶ We write uqv for the configuration where:
 - ▶ the tape to the left of the current position contains u ;
 - ▶ the tape to the right of the current position (and including the current position) contains v (followed by an infinite number of $_$'s);
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 - ▶ the machine is in state q .
- ▶ For example, $01q_3110$ describes the following situation:



Turing machines: formal definition (3)

- ▶ Configuration C_1 **yields** C_2 if M can go from C_1 to C_2 in one step. So:
 - ▶ uaq_jbv yields uq_kacv if $\delta(q_j, b) = (q_k, c, L)$;
 - ▶ uaq_jbv yields $uacq_kv$ if $\delta(q_j, b) = (q_k, c, R)$.

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- ▶ If M is at the left-hand end of the tape, it cannot move any further to the left; but M can move arbitrarily far to the right (the tape is **one-way infinite**).
- ▶ M **accepts** input x if there is a sequence of configurations C_1, \dots, C_k such that:
 1. C_1 is the start configuration of M on input x ;
 2. For all $1 \leq i \leq k - 1$, C_i yields C_{i+1} ;
 3. C_k is an accepting configuration (M is in state q_{accept}).

Real-world implementations

As well as being a mathematical tool, a Turing machine is a real machine that we can build...

- ▶ <http://aturingmachine.com/index.php>
- ▶ <http://www.legoturingmachine.org>

Summary and further reading

- ▶ A Turing machine is a generalisation of a finite automaton which has access to an infinite tape which it can read from and write to.
- ▶ Turing machines can perform complicated computations (although writing these down formally can be a painful process).
- ▶ Further reading: Sipser §3.1.